

## 5.4 Pook's Book

7.1 (LAY's book)

### Orthogonal Diagonalization or Diagonalization of Symmetric Matrices

Def -  $A, B$   $n \times n$  matrices

$A$  and  $B$  are orthogonal similar if there is an orthogonal matrix  $P$  such that

$$P^T A P = B$$

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Def. - If  $A$  is orthogonal similar to a diagonal matrix  $D$

$$P^T A P = D,$$

we say that  $A$  is orthogonal diagonalizable and that  $P$  orthogonally diagonalizes  $A$ .

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## Theory for Symmetric Matrices

Thm 5.17 If  $A$  is orthogonally diagonalizable, then  $A$  is symmetric.

Proof.  $A$  O.D  $\Rightarrow$  There is  $Q$  orthogonal s.t.

$$Q^T A Q = D \Leftrightarrow A = Q D Q^T$$

Then,  $A^T = (Q D Q^T)^T = Q D^T Q^T = Q D Q^T = A. \checkmark$

This result implies that the only possible diagonalizable matrices are the symmetric matrices.

Thm 5.18 If  $A$  is real and symmetric, then the eigenvalues of  $A$  are real.

Proof. (Book)

Thm 5.19 If  $A$  is symmetric and  $\lambda_1 \neq \lambda_2$  are two eigenvalues of  $A$  with corresponding eigenvectors  $\vec{v}_1$  and  $\vec{v}_2$ , respect.

Then  $\vec{v}_1 \cdot \vec{v}_2 = 0$

Proof.  $\lambda_1 (\vec{v}_1 \cdot \vec{v}_2) = \lambda_1 \vec{v}_1 \cdot \vec{v}_2 = A \vec{v}_1 \cdot \vec{v}_2 = (A \vec{v}_1)^T \vec{v}_2$   
 $= \vec{v}_1^T (A^T \vec{v}_2) = \vec{v}_1^T (A \vec{v}_2) = \vec{v}_1^T \lambda_2 \vec{v}_2$   
 $= \lambda_2 \vec{v}_1^T \vec{v}_2 = \lambda_2 (\vec{v}_1 \cdot \vec{v}_2) \Leftrightarrow (\lambda_2 - \lambda_1) \vec{v}_1 \cdot \vec{v}_2 = 0$   
 $\Rightarrow \boxed{\vec{v}_1 \cdot \vec{v}_2 = 0}$

Thm 5.20 If  $A_{n \times n}$  real matrix, then  $A$  is symmetric if and only if  $A$  is orthogonally diagonalizable.

Proof. ( $\leftarrow$ ) Done in theorem 5.17.

( $\rightarrow$ ) book.

Another important result is

Thm If  $\vec{u}_1$  and  $\vec{u}_2$  are two eigenvectors of the same eigenvalue  $\lambda$ , then any linear

combination:  $C_1 \vec{u}_1 + C_2 \vec{u}_2$

is also an eigenvector of  $\lambda$ .

Proof. We know  $A\vec{u}_1 = \lambda \vec{u}_1$  and  $A\vec{u}_2 = \lambda \vec{u}_2$  then,

$$\begin{aligned} A(C_1 \vec{u}_1 + C_2 \vec{u}_2) &= C_1 A\vec{u}_1 + C_2 A\vec{u}_2 \\ &= C_1 \lambda \vec{u}_1 + C_2 \lambda \vec{u}_2 \\ &= \lambda (C_1 \vec{u}_1 + C_2 \vec{u}_2) \end{aligned}$$

Therefore,  $C_1 \vec{u}_1 + C_2 \vec{u}_2$  is also an eigenvector for  $\lambda$ .

Consider

$$A = \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix}$$

Compare with matrix  
A in sect 5.3

$$A = \begin{bmatrix} 0 & -1 & -1 \\ 1 & 2 & 1 \\ -1 & -1 & 0 \end{bmatrix}$$

Exercise

Determine if the matrix  $A$  is diagonalizable and if so, find  $P$  invertible and  $D$  diagonal such that  $P^{-1}AP = D$ .

Ans:

For  $A_{n \times n}$  to be diagonalizable, we need to find out  $n$  linearly indep eigenvectors.

In fact,

$$|A - \lambda I| = \begin{vmatrix} 2-\lambda & -1 & -1 \\ -1 & 2-\lambda & -1 \\ -1 & -1 & 2-\lambda \end{vmatrix} = 0$$

$$\Leftrightarrow (2-\lambda)^3 - 1 - 1 - (2-\lambda + 2-\lambda + 2-\lambda)$$

$$= (2-\lambda)^3 - 2 - 3(2-\lambda) = 0 \dots \dots \dots$$

$$\Leftrightarrow \lambda(\lambda-3)^2 = 0 \Rightarrow \begin{cases} \lambda_1 = 0 \\ \lambda_2 = 3 \end{cases} \text{ Eigenvalues of } A.$$

For  $\lambda_2 = 3$

$$(A - 3I)\vec{x} = \vec{0}$$

$$\Leftrightarrow \begin{bmatrix} -1 & -1 & -1 \\ -1 & -1 & -1 \\ -1 & -1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$A \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow x_1 = -x_2 - x_3, \quad x_2, x_3 \text{ free Variables}$$

Eigenvectors corresponding to  $\lambda_2 = 3$

$$\vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -x_2 - x_3 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -x_2 \\ x_2 \\ 0 \end{bmatrix} + \begin{bmatrix} -x_3 \\ 0 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}$$

$\mathcal{B} \left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$  form a basis for the eigenspace corresponding to  $\lambda_2 = 3$ . (clearly lin. indep.)

For  $\lambda_1 = 0$

$$(A - 0I)\vec{x} = \vec{0} \Leftrightarrow \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$A \sim \begin{bmatrix} 1 & 1 & -2 \\ 0 & 3 & -3 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow x_2 = x_3, \quad x_1 = 2x_3 - x_2 = x_3.$$

$$\text{Eigenvectors corresponding to } \lambda_1 = 0 \Rightarrow \vec{x} = \begin{bmatrix} x_3 \\ x_3 \\ x_3 \end{bmatrix} = x_3 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \rightarrow \vec{u}_1$$

The set of eigenvectors

$\{\vec{u}_1, \vec{u}_2, \vec{u}_3\}$  is lin. indep. why?

Therefore,  $A$  is diagonalizable and

$$P^{-1}AP = D$$

where  $P = [\vec{u}_1 \ \vec{u}_2 \ \vec{u}_3] = \begin{bmatrix} 1 & -1 & -1 \\ 1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}$

and  $D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$

Notice that  $\boxed{\vec{u}_1 \perp \vec{u}_2}$  and  $\boxed{\vec{u}_1 \perp \vec{u}_3}$  but  $\vec{u}_2 \not\perp \vec{u}_3$ .

Question: Can we find an orthogonal set of eigenvectors for  $A$  from  $\{\vec{u}_1, \vec{u}_2, \vec{u}_3\}$ ?

The answer is "yes"

Since  $\vec{u}_1$  is already orthogonal to  $\vec{u}_2$  and  $\vec{u}_3$

We will keep  $\vec{u}_1$  and  $\vec{u}_2$  and we will find a third vector  $\vec{u}_3'$  orthogonal to both  $\vec{u}_1$  and  $\vec{u}_2$ .

In fact, we only need  $\vec{u}_3'$  to be orthogonal to  $\frac{\vec{u}_2}{\|\vec{u}_2\|}$ , because  $\vec{u}_1$  will automatically be orthogonal

to  $\vec{u}_3'$ , since  $\vec{u}_3'$  will be a linear comb. of  $\vec{u}_3$  and  $\vec{u}_2$ .

$$\text{So, } \hat{u}_2 = \frac{\vec{u}_2}{\|\vec{u}_2\|} = \begin{bmatrix} -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \quad \langle \vec{u}_3, \hat{u}_2 \rangle$$

then, using Gram-Schmidt process  $\parallel$

$$\vec{u}_3' = \vec{u}_3 - \langle \vec{u}_3, \hat{u}_2 \rangle \hat{u}_2 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} - \frac{1}{\sqrt{2}} \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}$$

$$= \begin{bmatrix} -1 + 1/2 \\ -1/2 \\ 1 \end{bmatrix} = \begin{bmatrix} -1/2 \\ -1/2 \\ 1 \end{bmatrix}, \quad \|\vec{u}_3'\| = \sqrt{\frac{1}{4} + \frac{1}{4} + 1} = \frac{\sqrt{6}}{2}$$

It can be easily seen that

$$\left\langle \vec{u}_3', \frac{\vec{u}_2}{\|\vec{u}_2\|} \right\rangle = 0 \quad \text{and} \quad \langle \vec{u}_3', \vec{u}_1 \rangle = 0$$

Also,  $\vec{u}_3'$  is also an eigenvector corresponding to  $\lambda_2 = 3$

$$\begin{aligned} \text{Since } A\vec{u}_3' &= A\vec{u}_3 - \langle \vec{u}_3, \hat{u}_2 \rangle A\hat{u}_2 = \lambda_2 \vec{u}_3 - \lambda_2 \langle \vec{u}_3, \hat{u}_2 \rangle \hat{u}_2 \\ &= \lambda_2 (\vec{u}_3 - \langle \vec{u}_3, \hat{u}_2 \rangle \hat{u}_2) = \lambda_2 \vec{u}_3' \end{aligned}$$

By normalizing  $\tilde{u}_1$  and  $\tilde{u}_3'$ , we obtain an orthogonal matrix  $P$  of eigenvectors of  $A$

$$S = \{\hat{u}_1, \hat{u}_2, \hat{u}_3\} = \left\{ \begin{bmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}, \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix}, \begin{bmatrix} -1/\sqrt{6} \\ -1/\sqrt{6} \\ 2/\sqrt{6} \end{bmatrix} \right\}$$

Thus, there is  $\hat{P}$  invertible matrix such that

$$\hat{P}^{-1} A \hat{P} = D \text{ which is equiv. } \boxed{\hat{P}^T A \hat{P} = D.}$$

Where

$$\hat{P} = \begin{bmatrix} 1/\sqrt{3} & -1/\sqrt{2} & -1/\sqrt{6} \\ 1/\sqrt{3} & 1/\sqrt{2} & -1/\sqrt{6} \\ 1/\sqrt{3} & 0 & 2/\sqrt{6} \end{bmatrix} \text{ and } D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

Thus, using thm 7.2.1  $A$  is orthogonally diagonalizable

There is  $\hat{P}$  such that  $\boxed{\hat{P}^T A \hat{P} = D}$

where

$$\hat{P} = \begin{bmatrix} \hat{u}_1 & \hat{u}_2 & \hat{u}_3 \\ 1/\sqrt{3} & -1/\sqrt{2} & -1/\sqrt{6} \\ 1/\sqrt{3} & 1/\sqrt{2} & -1/\sqrt{6} \\ 1/\sqrt{3} & 0 & 2/\sqrt{6} \end{bmatrix} \text{ and } D = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$$

### Spectral Decomposition of a Matrix $A$ .

First, consider the product of

$$\begin{aligned} & \begin{bmatrix} \hat{c}_1 & \hat{c}_2 \\ a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{bmatrix} \begin{bmatrix} \hat{r}_1 \\ \hat{r}_2 \end{bmatrix} = \begin{bmatrix} a_{11}b_{11} + a_{12}b_{21} & a_{11}b_{12} + a_{12}b_{22} \\ a_{21}b_{11} + a_{22}b_{21} & a_{21}b_{12} + a_{22}b_{22} \end{bmatrix} \\ &= \begin{bmatrix} a_{11}b_{11} & a_{11}b_{12} \\ a_{21}b_{11} & a_{21}b_{12} \end{bmatrix} + \begin{bmatrix} a_{12}b_{21} & a_{12}b_{22} \\ a_{22}b_{21} & a_{22}b_{22} \end{bmatrix} = \\ &= \begin{bmatrix} a_{11} \\ a_{21} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} \end{bmatrix} + \begin{bmatrix} a_{12} \\ a_{22} \end{bmatrix} \begin{bmatrix} b_{21} & b_{22} \end{bmatrix} = \end{aligned}$$

$$= \hat{c}_1 \hat{r}_1 + \hat{c}_2 \hat{r}_2.$$

This result is true for general  $A, B$   $n \times n$  matrices.

# Spectral Decomposition

$$U = \begin{bmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{bmatrix} = [\vec{u}_1 \quad \vec{u}_2], \text{ where } \vec{u}_1 = \begin{bmatrix} u_{11} \\ u_{21} \end{bmatrix}$$

$$U^T = \begin{bmatrix} u_{11} & u_{21} \\ u_{12} & u_{22} \end{bmatrix} = \begin{bmatrix} \vec{u}_1^T \rightarrow \\ \vec{u}_2^T \rightarrow \end{bmatrix} \quad \vec{u}_2 = \begin{bmatrix} u_{12} \\ u_{22} \end{bmatrix}$$

Notice that

$$U U^T = \vec{u}_1 \vec{u}_1^T + \vec{u}_2 \vec{u}_2^T$$

Proof.

$$\begin{aligned} U U^T &= \begin{bmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{bmatrix} \begin{bmatrix} u_{11} & u_{21} \\ u_{12} & u_{22} \end{bmatrix} \\ &= \begin{bmatrix} u_{11} u_{11} + u_{12} u_{12} & u_{11} u_{21} + u_{12} u_{22} \\ u_{21} u_{11} + u_{22} u_{12} & u_{21} u_{21} + u_{22} u_{22} \end{bmatrix} \\ &= \begin{bmatrix} u_{11} u_{11} & u_{11} u_{21} \\ u_{21} u_{11} & u_{21} u_{21} \end{bmatrix} + \begin{bmatrix} u_{12} u_{12} & u_{12} u_{22} \\ u_{22} u_{12} & u_{22} u_{22} \end{bmatrix} \end{aligned}$$

Also,

$$\begin{aligned}
 \vec{u}_1 \vec{u}_1^T + \vec{u}_2 \vec{u}_2^T &= \begin{bmatrix} u_{11} \\ u_{21} \end{bmatrix} \begin{bmatrix} u_{11} & u_{21} \end{bmatrix} \\
 &+ \begin{bmatrix} u_{12} \\ u_{22} \end{bmatrix} \begin{bmatrix} u_{12} & u_{22} \end{bmatrix} \\
 &= \begin{bmatrix} u_{11} u_{11} & u_{11} u_{21} \\ u_{21} u_{11} & u_{21} u_{21} \end{bmatrix} + \begin{bmatrix} u_{12} u_{12} & u_{12} u_{22} \\ u_{22} u_{12} & u_{22} u_{22} \end{bmatrix} \\
 &= V V^T \quad \checkmark
 \end{aligned}$$

Spectral decomposition of a matrix  $A_{2 \times 2}$  real and Symmetric

$$\begin{aligned}
 A &= V D V^T = \begin{bmatrix} \vec{u}_1 & \vec{u}_2 \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} \vec{u}_1^T \rightarrow \\ \vec{u}_2^T \rightarrow \end{bmatrix} \\
 &= \lambda_1 \vec{u}_1 \vec{u}_1^T + \lambda_2 \vec{u}_2 \vec{u}_2^T.
 \end{aligned}$$

In fact,

$$\begin{aligned}
 A &= U D U^T = \begin{bmatrix} u_{11} & u_{12} \\ u_{21} & u_{22} \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} \begin{bmatrix} u_{11} & u_{21} \\ u_{12} & u_{22} \end{bmatrix} \\
 &= \left( \begin{bmatrix} u_{11} \\ u_{21} \end{bmatrix} [\lambda_1 \ 0] + \begin{bmatrix} u_{12} \\ u_{22} \end{bmatrix} [0 \ \lambda_2] \right) \begin{bmatrix} u_{11} & u_{21} \\ u_{12} & u_{22} \end{bmatrix} \\
 &= \left( \begin{bmatrix} \lambda_1 u_{11} & 0 \\ \lambda_1 u_{21} & 0 \end{bmatrix} + \begin{bmatrix} 0 & \lambda_2 u_{12} \\ 0 & \lambda_2 u_{22} \end{bmatrix} \right) \begin{bmatrix} u_{11} & u_{21} \\ u_{12} & u_{22} \end{bmatrix} \\
 &= \begin{bmatrix} \lambda_1 u_{11} & \lambda_2 u_{12} \\ \lambda_1 u_{21} & \lambda_2 u_{22} \end{bmatrix} \begin{bmatrix} u_{11} & u_{21} \\ u_{12} & u_{22} \end{bmatrix} \\
 &= \lambda_1 \begin{bmatrix} u_{11} \\ u_{21} \end{bmatrix} \begin{bmatrix} u_{11} & u_{21} \end{bmatrix} + \lambda_2 \begin{bmatrix} u_{12} \\ u_{22} \end{bmatrix} \begin{bmatrix} u_{12} & u_{22} \end{bmatrix} \\
 &= \lambda_1 \vec{u}_1 \vec{u}_1^T + \lambda_2 \vec{u}_2 \vec{u}_2^T.
 \end{aligned}$$

Now, if for a given matrix  $A_{n \times n}$  symmetric

$\lambda_1, \dots, \lambda_n$  are eigenvalues with corresp orthonormal eigenvectors

$\vec{u}_1, \dots, \vec{u}_n$ , then

$$D = P^T A P$$

$$\Rightarrow A = P D P^T = \begin{bmatrix} \vec{u}_1 & \vec{u}_2 & \dots & \vec{u}_n \\ \downarrow & \downarrow & & \downarrow \end{bmatrix} \begin{bmatrix} \lambda_1 & 0 & \dots & 0 \\ 0 & \lambda_2 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & \lambda_n \end{bmatrix} \begin{bmatrix} \vec{u}_1^T \rightarrow \\ \vec{u}_2^T \rightarrow \\ \vdots \\ \vec{u}_n^T \rightarrow \end{bmatrix}$$

$$= \begin{bmatrix} \lambda_1 \vec{u}_1 & \lambda_2 \vec{u}_2 & \dots & \lambda_n \vec{u}_n \end{bmatrix} \begin{bmatrix} \vec{u}_1^T \rightarrow \\ \vec{u}_2^T \rightarrow \\ \vdots \\ \vec{u}_n^T \rightarrow \end{bmatrix}$$

From previous  
comput.

$$= \lambda_1 \vec{u}_1 \vec{u}_1^T + \lambda_2 \vec{u}_2 \vec{u}_2^T + \dots + \lambda_n \vec{u}_n \vec{u}_n^T$$

Summarizing,

$$A = \lambda_1 \vec{u}_1 \vec{u}_1^T + \lambda_2 \vec{u}_2 \vec{u}_2^T + \dots + \lambda_n \vec{u}_n \vec{u}_n^T \quad (16.1)$$

This expression is called Spectral Decomposition of  $A$

In our previous exercise,

$$\begin{aligned} \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & -1 \\ -1 & -1 & 2 \end{bmatrix} &= 0 \begin{bmatrix} 1/\sqrt{3} \\ 1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix} \begin{bmatrix} 1/\sqrt{3} & 1/\sqrt{3} & 1/\sqrt{3} \end{bmatrix} + 3 \begin{bmatrix} -1/\sqrt{2} \\ 1/\sqrt{2} \\ 0 \end{bmatrix} \begin{bmatrix} -1/\sqrt{2} & 1/\sqrt{2} & 0 \end{bmatrix} + \\ &\quad + 3 \begin{bmatrix} -1/\sqrt{6} \\ -1/\sqrt{6} \\ 2/\sqrt{6} \end{bmatrix} \begin{bmatrix} -1/\sqrt{6} & -1/\sqrt{6} & 2/\sqrt{6} \end{bmatrix} \\ &= 3 \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} & 0 \\ -\frac{1}{2} & \frac{1}{2} & 0 \\ 0 & 0 & 0 \end{bmatrix} + 3 \begin{bmatrix} \frac{1}{6} & \frac{1}{6} & -\frac{2}{6} \\ \frac{1}{6} & \frac{1}{6} & -\frac{2}{6} \\ -\frac{2}{6} & -\frac{2}{6} & \frac{4}{6} \end{bmatrix} \end{aligned}$$

## Geometric Interpretation of a Spectral Decomposition.

It can be proved that by multiplying

$$\vec{u} \vec{u}^T \vec{x} = \text{proj}_{\text{Span}\{\vec{u}\}} \vec{x}$$

Therefore, the spectral decomposition (16.1) applied to a vector  $\vec{x}$  can be obtained by projecting  $\vec{x}$  orthogonally on the lines determined by the eigenvectors of  $A$ , then multiplying these projections by the eigenvalues, and finally adding the scaled projections.

How Figure 7.2.1 for example 2 (book)

$$A = \begin{bmatrix} 1 & 2 \\ 2 & -2 \end{bmatrix} \quad \text{Eigenvalues}$$

$$\lambda_1 = -3 \rightarrow \vec{u}_1 = \begin{bmatrix} 1/\sqrt{5} \\ -2/\sqrt{5} \end{bmatrix}$$

$$\lambda_2 = 2 \rightarrow \vec{u}_2 = \begin{bmatrix} 2/\sqrt{5} \\ 1/\sqrt{5} \end{bmatrix}$$

Orthonormal set of eigenvectors

For example

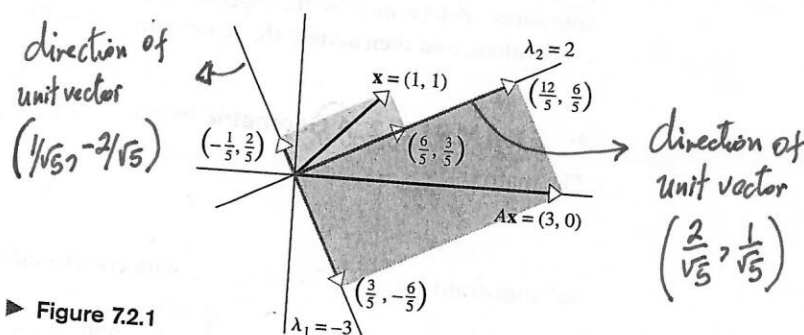
$$A \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \left( \lambda_1 \vec{u}_1 \vec{u}_1^T + \lambda_2 \vec{u}_2 \vec{u}_2^T \right) \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 2 & -2 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = -3 \begin{bmatrix} \frac{1}{5} & -\frac{2}{5} \\ -\frac{2}{5} & \frac{4}{5} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} + 2 \begin{bmatrix} \frac{4}{5} & \frac{2}{5} \\ \frac{2}{5} & \frac{1}{5} \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$\text{Notice that } \left[ = (-3) \begin{bmatrix} -1/5 \\ 2/5 \end{bmatrix} + (2) \begin{bmatrix} 6/5 \\ 3/5 \end{bmatrix} = \begin{bmatrix} 3/5 \\ 6/5 \end{bmatrix} + \begin{bmatrix} 12/5 \\ 6/5 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \end{bmatrix} \right]$$

$$\text{proj}_{\begin{pmatrix} 1/\sqrt{5}, -2/\sqrt{5} \end{pmatrix}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \left[ (1, 1) \cdot (1/\sqrt{5}, -2/\sqrt{5}) \right] (1/\sqrt{5}, -2/\sqrt{5}) = \frac{-1}{\sqrt{5}} (1/\sqrt{5}, -2/\sqrt{5}) = \left( -\frac{1}{5}, \frac{2}{5} \right)$$

Formulas (9) and (10) provide two different ways of viewing the image of the vector  $(1, 1)$  under multiplication by  $A$ : Formula (9) tells us directly that the image of this vector is  $(3, 0)$ , whereas Formula (10) tells us that this image can also be obtained by projecting  $(1, 1)$  onto the eigenspaces corresponding to  $\lambda_1 = -3$  and  $\lambda_2 = 2$  to obtain the vectors  $(-\frac{1}{5}, \frac{2}{5})$  and  $(\frac{6}{5}, \frac{3}{5})$ , then scaling by the eigenvalues to obtain  $(\frac{3}{5}, -\frac{6}{5})$  and  $(\frac{12}{5}, \frac{6}{5})$ , and then adding these vectors (see Figure 7.2.1). ◀



► Figure 7.2.1

### The Nondiagonalizable Case

If  $A$  is an  $n \times n$  matrix that is not orthogonally diagonalizable, it may still be possible to achieve considerable simplification in the form of  $P^TAP$  by choosing the orthogonal matrix  $P$  appropriately. We will consider two theorems (without proof) that illustrate this. The first, due to the German mathematician Issai Schur, states that every square matrix  $A$  is orthogonally similar to an upper triangular matrix that has the eigenvalues of  $A$  on the main diagonal.

### THEOREM 7.2.3 Schur's Theorem

If  $A$  is an  $n \times n$  matrix with real entries and real eigenvalues, then there is an orthogonal matrix  $P$  such that  $P^TAP$  is an upper triangular matrix of the form

$$P^TAP = \begin{bmatrix} \lambda_1 & \times & \times & \cdots & \times \\ 0 & \lambda_2 & \times & \cdots & \times \\ 0 & 0 & \lambda_3 & \cdots & \times \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & \lambda_n \end{bmatrix} \quad (11)$$

in which  $\lambda_1, \lambda_2, \dots, \lambda_n$  are the eigenvalues of the matrix  $A$  repeated according to multiplicity.



Issai Schur  
(1875–1941)

**Historical Note** The life of the German mathematician Issai Schur is a sad reminder of the effect that Nazi policies had on Jewish intellectuals during the 1930s. Schur was a brilliant mathematician and a popular lecturer who attracted many students and researchers to the University of Berlin, where he worked and taught. His lectures sometimes attracted so many students that opera glasses were needed to see him from the back row. Schur's life became increasingly difficult under Nazi rule, and in April of 1933 he was forced to "retire" from the university under a law that prohibited non-Aryans from holding "civil service" positions. There was an outcry from many of his students and colleagues who respected and liked him, but it did not stave off his complete dismissal in 1935. Schur, who thought of himself as a loyal German never understood the persecution and humiliation he received at Nazi hands. He left Germany for Palestine in 1939, a broken man. Lacking in financial resources, he had to sell his beloved mathematics books and lived in poverty until his death in 1941.

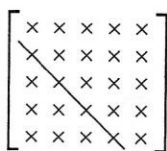
[Image: Courtesy Electronic Publishing Services, Inc., New York City]

It is common to denote the upper triangular matrix in (11) by  $S$  (for Schur), in which case that equation can be rewritten as

$$A = PSP^T \quad (12)$$

which is called a **Schur decomposition** of  $A$ .

The next theorem, due to the German mathematician and engineer Karl Hessenberg (1904–1959), states that every square matrix with real entries is orthogonally similar to a matrix in which each entry below the first **subdiagonal** is zero (Figure 7.2.2). Such a matrix is said to be in **upper Hessenberg form**.



First subdiagonal

▲ Figure 7.2.2

Note that unlike those in (11), the diagonal entries in (13) are usually *not* the eigenvalues of  $A$ .

#### THEOREM 7.2.4 Hessenberg's Theorem

If  $A$  is an  $n \times n$  matrix, then there is an orthogonal matrix  $P$  such that  $P^TAP$  is a matrix of the form

$$P^TAP = \begin{bmatrix} \times & \times & \cdots & \times & \times & \times \\ \times & \times & \cdots & \times & \times & \times \\ 0 & \times & \ddots & \times & \times & \times \\ \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & \times & \times & \times \\ 0 & 0 & \cdots & 0 & \times & \times \end{bmatrix} \quad (13)$$

It is common to denote the upper Hessenberg matrix in (13) by  $H$  (for Hessenberg), in which case that equation can be rewritten as

$$A = PHP^T \quad (14)$$

which is called an **upper Hessenberg decomposition** of  $A$ .

**Remark** In many numerical algorithms the initial matrix is first converted to upper Hessenberg form to reduce the amount of computation in subsequent parts of the algorithm. Many computer packages have built-in commands for finding Schur and Hessenberg decompositions.

#### Concept Review

- Orthogonally similar matrices
- Orthogonally diagonalizable matrix
- Spectral decomposition (or eigenvalue decomposition)
- Schur decomposition
- Subdiagonal
- Upper Hessenberg form
- Upper Hessenberg decomposition

#### Skills

- Be able to recognize an orthogonally diagonalizable matrix.
- Know that eigenvalues of symmetric matrices are real numbers.
- Know that for a symmetric matrix eigenvectors from different eigenspaces are orthogonal.
- Be able to orthogonally diagonalize a symmetric matrix.
- Be able to find the spectral decomposition of a symmetric matrix.
- Know the statement of Schur's Theorem.
- Know the statement of Hessenberg's Theorem.